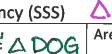
Name:		
Date:		

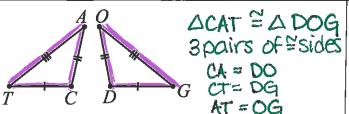
Proving Triangles Congruent

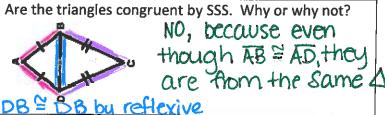
look for + reflexive -sides -angles

1. Side-Side-Side Triangle Congruency (SSS)

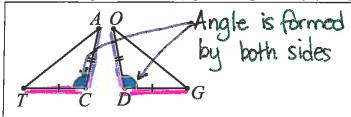


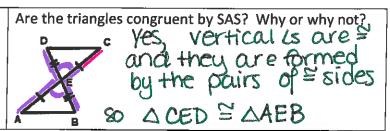
hidden givens => + vertical Ls



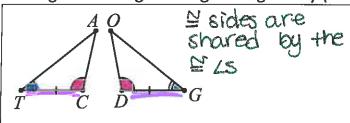


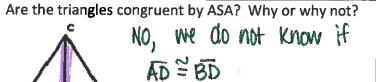
2. Side-Angle-Side Triangle Congruency (SAS)



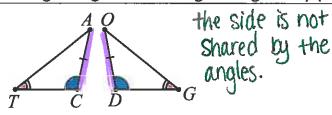


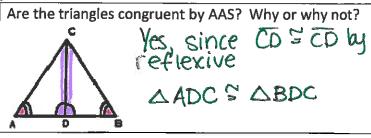
3. Angle-Side-Angle Triangle Congruency (ASA)



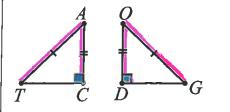


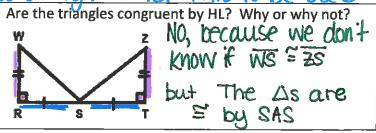
4. Angle-Angle-Side Triangle Congruency (AAS)





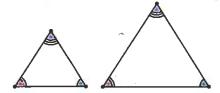
5. Hypotenuse-Leg (HL) - You must have a right L for this to be used!





Methods that DO NOT prove Triangles to be Congruent

AAA



Why does AAA not guarantee congruent triangles? Dilations preserve 4 measure hot length.

No swearing ASS (or SSA) "Donkey in math theory class!" It is not Nice!!

Why does ASS not guarantee congruent triangles?

2 different Sized Δ 's can be formed from $\mathbb{O}.A$

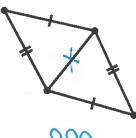
Examples: Which triangle postulate (if any) shows that the triangles are congruent?

1



AAS

2.

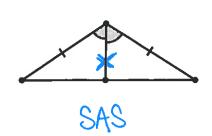


222

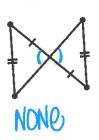
3.



4.

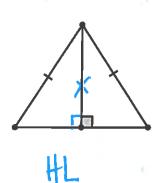


5.



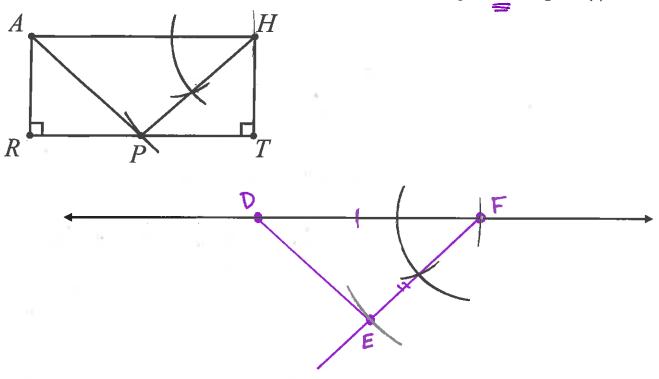
"DONKEY THM"

6.

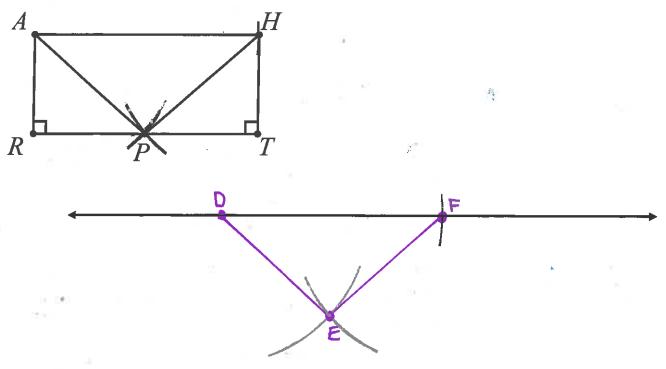


Justifying Congruent Triangles Using Constructions:

1. On the line, construct and Label ΔDEF so that $\Delta DEF \cong \Delta APH$ using the SAS congruency postulate.

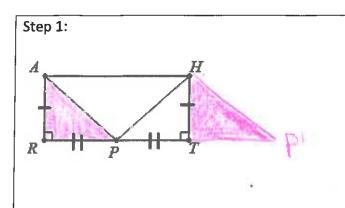


2. On the line, construct and Label ΔDEF so that $\Delta DEF \cong \Delta APH$ using the SSS congruency postulate.



Justifying Congruent Triangles Using Rigid Motions:

1. Use Rigid Motions to Prove: $\triangle ARP \cong \triangle HTP$



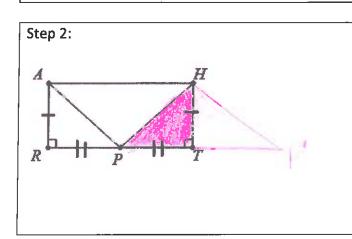


Result: (State where each point maps to) = This forms \triangle HTP! where R->T. Pap' & AaH

Reasoning: (Justify why the mappings are valid)

RAT because of the defined vector

RT. A>H because AR = HT and LR= LT b/c translation preserves L'measure à distance:

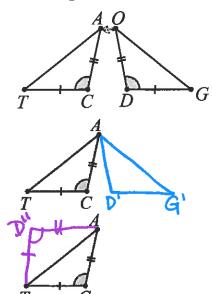


Action: Reflect AHTP' over HT

Result: This forms Δ THP where T>T, H>H and P'>P

Reasoning: T & H remain the same since they are on HT, P'>P because TP & TP' and reflection preserves the distance.

2. Use Rigid Motions To Prove: $\triangle CAT \cong \triangle DOG$



Translate Δ Dog along vector \overrightarrow{OA} , this moves

o⇒A °

D>D! because of, this makes DCATEDDAG!
G>G's since translation is a rigid motion, distance & L measure the preserved

- (2) Rotate AD'AG' about point A counterclack-Wise Since Rotations are rigid motions use non have $\Delta CAT \cong \Delta D^{\parallel}AT$
- Reflect over AT forming & CAT. Since reflection is a rigid motion & AC = ADI and CT = D"T WE KNOW DD"AT = D CAT